

WE DIRECT DRIVE YOUR MOTION TECHNOLOGY

Direct drive motors from Tecnotion are seamlessly integrated into a wide range of applications, including semiconductors, machine tooling, robotics, display applications and printing. As an independent supplier of linear-, torque and vacuum motors, we offer specialized motor technology to place in your motion solutions.

We have distinguished ourselves for almost 30 years with the exclusive development and production of direct drive linear and torque motors. As a result, we succeed in providing the best motor solution for your motion needs, whether it is a catalogue or a custom motor. Thanks to our extensive experience we are used to designing and building any motion requirement with unmatched quality & performance.



UXX / UXA series

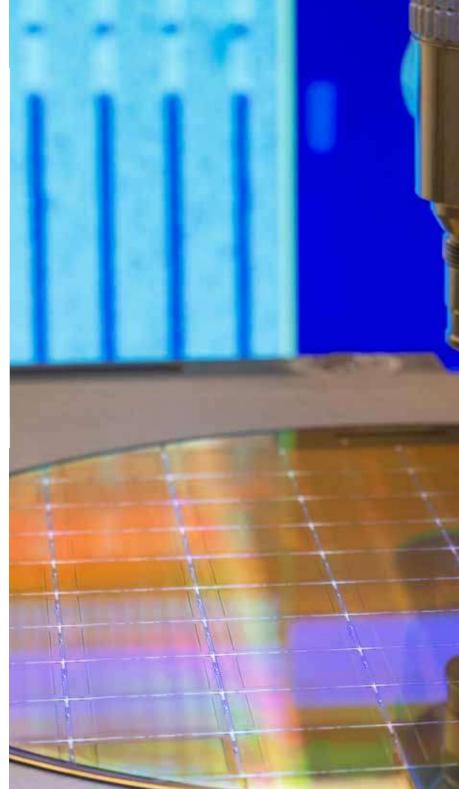
F_p 615-4200 N F_c 120-846 N

The UXX is the most powerful standard ironless motor we have to offer. It is ideal for heavy duty industrial applications that demand ultra precision and maximum force output. The UXA is the economical alternative to the UXX. It's slightly less powerful, but makes up for this with a smaller footprint and an attractive price tag.

UL series

F_p 240-1200 N F_c 70-350 N

The high-end UL ironless motors are available in various configurations that can easily be adapted to application specific requirements. Because of their high speed, positioning accuracy, zero cogging and attraction force, many UL motors are successfully applied throughout the semiconductor industry.





J L 6 S M 12 N U = Ironless
L M = Series type
6 12 = Number of coils

6 12 = Number of coil
S N = Winding type







UM series

F_p 100-400 N F_c 29-116 N

The mid-range UM ironless motors stand out for their extremely high speed and exceptional thermal characteristics which are the result of our unique production techniques. This makes the compact UM motors especially suited for applications in which highly accurate measuring is required.

UF series

F_p 42.5-85 N F_c 19.5-39 N

The UF series is built specifically to sustain very high continuous forces for its footprint, which is only marginally larger than that of the UC. It is exceptionally suited for applications with high duty cycles, for instance in the medical and semiconductor markets or for pick & place systems.

UC series

F_p 36-72 N F_c 10-20 N

The UC is our smallest "off the shelf" motor. Weighing in at just a few grams, this versatile, compact and affordable motor is still able to sustain a continuous force of 10 or 20 N. Due to its low weight it is also suited to operate in a vertical application environment.

Features

Ironless linear motor series

Coil



High force density

More force in a small design means lowering footprint and it fits better in tight spaces.



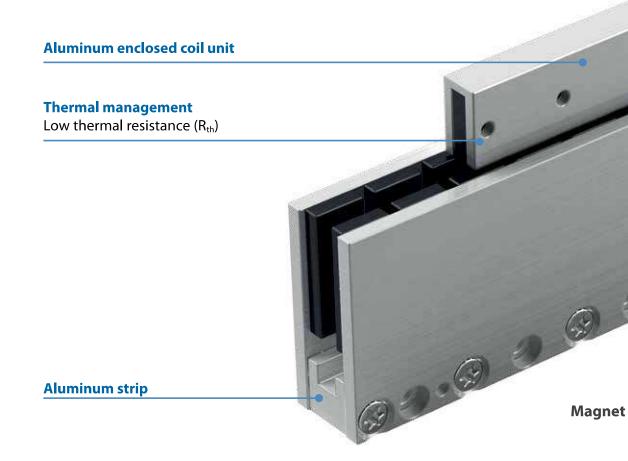
High acceleration and dynamics

The outstanding force to mass ratio of the ironless coils enables unmatched system dynamics.



Low thermal resistance

Allowing good heat transfer, achieving an extremely high continuous force for all motors when using a decent size heatsink or active cooling.





Power and sensor cable

Temperature measurement and cut-off sensor

Lifetime

Proven quality due to in-house testing

Manufacturing

Produced under high quality standards



Approved for CSA, CE, UKCA, REACH and RoHS

Ironless motors from Tecnotion are approved for CE, CSA, UKCA, REACH, and RoHS (UC and UF series are approved for CE, UKCA, REACH and RoHS).



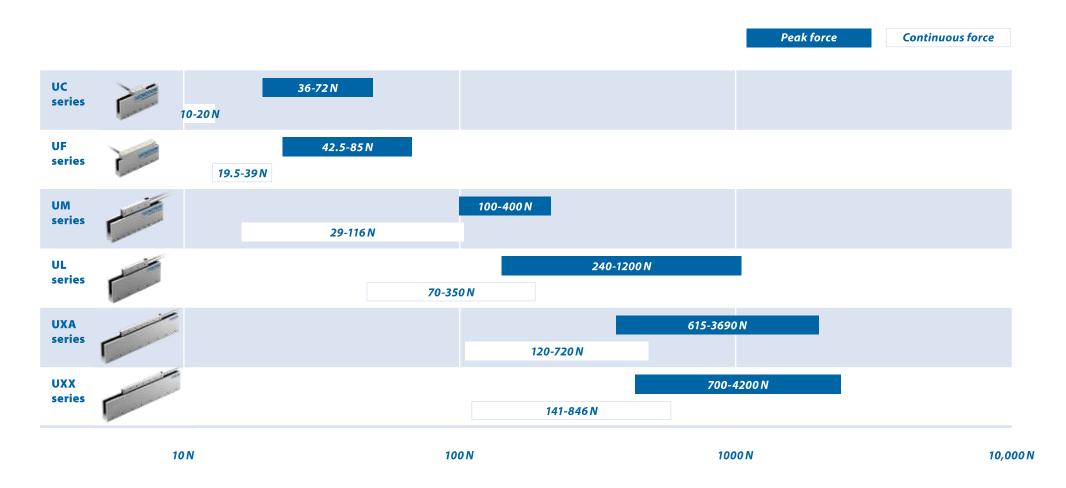
No cogging, extremely low force ripple

Ironless motors have no cogging effects, offering smooth motion and position accuracy in your application.

yoke

Accurate force constant and speed

Ironless motor force range



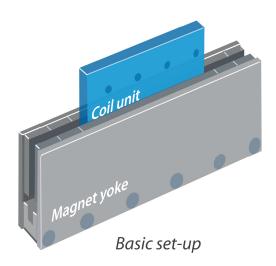
Modular

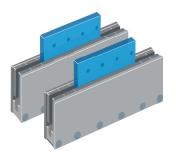
Motor configurations

The direct drive technology of ironless linear motors is a perfect way to enhance productivity. There is no attraction force or cogging between the coil unit and the magnet track. This gives ironless motors their light weight, superior precision, a linear force constant, and extremely dynamic velocity, acceleration, and deceleration.

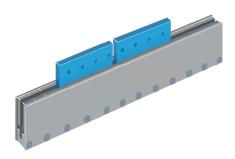
Motors can be mechanically aligned in series or parallel. This allows motors to move on different tracks, distributing even force to a large gantry, or on the same yoke track, enhancing power along a single line. In both cases, the total force of all motors adds up. Standardizing coil assemblies across multiple machines and applications reduces expenses and simplifies field support.

MODULAR SYSTEM All motors can be used in various configurations

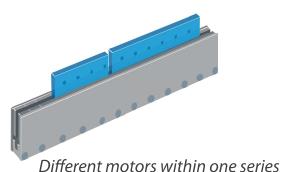




Parallel coupled coil



In-line on a single yoke





UC3 in 99mm magnet yoke shown

Magnet yoke dimensions							
Le (mm)	66	99	264				
M4 bolts	2 3 8						
Mass (kg/m) 3.2							
Magnet yokes c	an be bu	tted toge	ther.				



IECNOTION° direct drive in motion

UC series ironless

	Parameter	Remarks	Symbol	Unit	UC3 + UC3 inline	UC6
	Motor type, max voltage ph-ph	3-phase synchronous	U _{max}	V _{ac,rms} (V _{dc})	45	(60)
9	Peak force @ 20 K/s increase	magnets @ 25°C	Fp	N	36	72
Performance	Continuous force ¹	coils @ 80°C	F _c	N	10	20
rfor	Maximum speed ²	@ U _{max} @ F _c	V _{max}	m/s		5.0
a.	Motor force constant	$ I \leq I _c$	K_{f}	N/A_{rms}		1.4
	Motor constant	coils @ 25°C	S	N ² /W	9.2	18.1
	Peak current	magnets @ 25°C	I_p	A_{rms}	3.1	6.2
	Continuous current ¹	coils @ 80°C	I _c	A_{rms}	0.87	1.75
Electrical	Back EMF ph-ph _{peak}		$K_{\rm e}$	V _{dc} /m/s		9.3
Elect	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	4.7	2.4
	Induction per phase		L_{ph}	mH	0.75	0.38
	Electrical time constant		Τ _e	ms	().16
	Continuous power loss ¹	coils @ 80°C	P_c	W	13	26
Thermal	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	3.6	1.8
The	Thermal time constant	up to 63% max. coil temp.	τ_{th}	S		25
	Temperature sensor				n	one
	Coil unit mass	ex. cables	m	kg	0.031	0.062
	Coil unit length	ex. cables	L	mm	34	67
	Motor attraction force	rms @ 0 A	Fa	N		0
-	Magnet pitch NN		τ	mm	1	6.5
Mechanical	Cable mass			kg/m	(0.07
lech	Cable type (power)	length 1 m	d	mm (AWG)	4.3	3 (24)
2	Cable type (sensor)		d	mm (AWG)	n	one
	Cable life (power FLEX) ³	minimum		cycles	15,0	00,000
	Bending radius static (power FLEX)	minimum			5x cable	e diameter
	Bending radius dynamic (power FLEX)	minimum			8x cable	e diameter

¹ These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.

² Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.

³ Depending on bending radius, velocity and acceleration.

Coil units Magnet yokes M 3 (7,5 deep, 2xl Φ 4.5 (for M4 DIN 912) Hole Ø3 I2xI For Dowelpin DIN7 Ø3h8 (Optional use) UC 3/UC 6 UC 3 inline φ 7.5 B deepl UC 66mm UC 3 inline _M 3 17.5 deep, 2xl 0 0 2x UC 99mm M 3 (7.5 deep, 2xl **UC 264mm**



UF6 in 120mm magnet yoke shown

Magnet yoke dimensions					
Le (mm)	72	120			
M4 bolts	2	3			
Mass (kg/m) 3.2					
Magnet yokes can	be butted to	gether.			



1ECNOTION° direct drive in motion

UF series ironless

	Parameter	Remarks	Symbol	Unit	UF3	UF6
	Motor type, max voltage ph-ph	3-phase synchronous	U _{max}	$V_{ac,rms}\left(V_{dc}\right)$	45	(60)
9	Peak force @ 20 K/s increase	magnets @ 25°C	Fp	N	42.5	85
Performance	Continuous force ¹	coils @ 110°C	F _c	N	19.5	39
erfor	Maximum speed ²	@ U _{max} @ F _c	V _{max}	m/s	5	.1
<u>~</u>	Motor force constant	$ \leq $	K_{f}	N/A_{rms}	12	2.3
	Motor constant	coils @ 25°C	S	N ² /W	14.4	28.0
	Peak current	magnets @ 25°C	I_p	A_{rms}	3.5	6.9
	Continuous current ¹	coils @ 110°C	Ic	A_{rms}	1.58	3.17
Electrical	Back EMF ph-ph peak		K _e	V _{dc} /m/s	10	0.1
Elect	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	3.5	1.8
	Induction per phase		L_{ph}	mH	1.24	0.62
	Electrical time constant		τ_{e}	ms	0.	36
	Continuous power loss ¹	coils @ 110°C	P_c	W	35	70
Thermal	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	2.4	1.2
The	Thermal time constant	up to 63% max. coil temp.	τ_{th}	S	3	4
	Temperature sensor				N	TC
	Coil unit mass	ex. cables	m	kg	0.045	0.087
	Coil unit length	ex. cables	L	mm	49	97
	Motor attraction force	rms @ 0 A	F _a	N		0
ical	Magnet pitch NN		τ	mm	2	.4
Mechanical	Cable mass			kg/m	0.	07
Me	Cable type (power and sensor)	length 1 m	d	mm (AWG)	4.3	(24)
	Cable life (FLEX) ³	minimum		cycles	15,00	0,000
	Bending radius static	minimum			5x cable	diameter
	Bending radius dynamic	minimum			8x cable	diameter

¹ These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.

² Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.

³ Depending on bending radius, velocity and acceleration.

Coil units **Magnet yokes** 0 ֈ (Φ 4.5 (for M4 DIN 912) 8 (3 deep) UF 72mm M 3 (11 deep, 4x) UF3 UF 120mm DETAIL A Optional: Digital Hall Module ֈ 🛈 🛈 🕲 M 3 (11 deep, 2x) 2x UF 72mm @ 0.@@.O @ 0.@ UF 6

Mounting instructions and flatness or parallelism requirements can be found in the ironless installation manual. CAD files and 3D models can be downloaded from our website.

* All sizes are in mm



UM3 in 150mm magnet yoke shown

Magnet yoke dimensions								
Le (mm)	90	120	150	390				
M4 bolts	3 4 5 13							
Mass (kg/m) 4.8								
Magnet yokes	an be b	utted to	gether.					

IECNOTION° direct drive in motion

UM series ironless

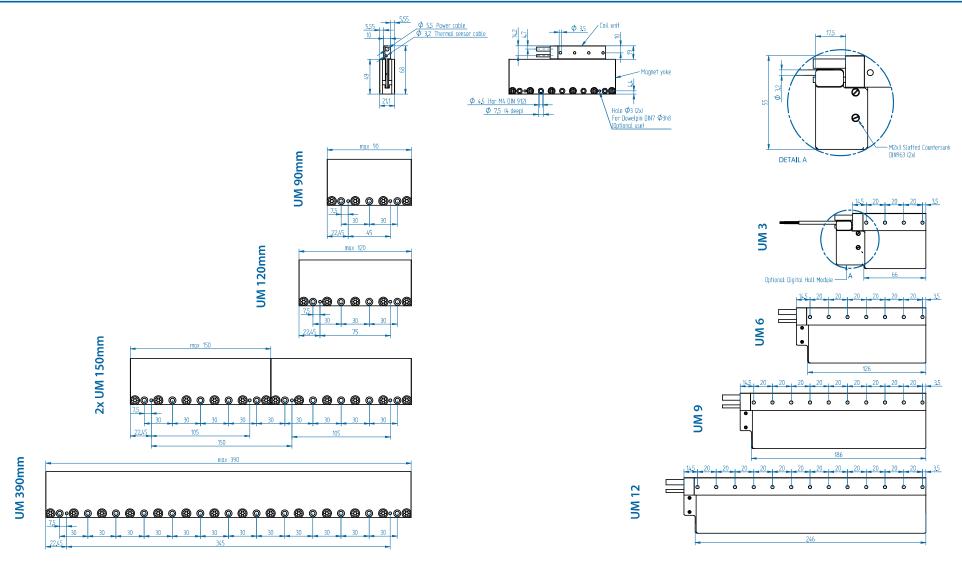
	Parameter	Remarks	Symbol	Unit	UI	M3	UM6		UM9		UM12	
	Winding type				N	S	N	S	N	S	N	S
	Motor type, max voltage ph-ph	3-phase synchronous	U _{max}	$V_{ac,rms}\left(V_{dc}\right)$				230	(325)			
ē	Peak force @ 20 K/s increase	magnets @ 25°C	F_p	N	10	100		0	300		400	
man	Continuous force ¹	coils @ 110°C	F _c	N	2	29	58	3	8	7	11	6
Performance	Continuous force ^{1,3}	coils @ 105°C	F _c	N	2	28	57	7	8	5	113	
P	Maximum speed ²	@ U _{max} @ F _c	V _{max}	m/s	10	18	10	18	10	18	10	18
	Motor force constant	l ≤ l _c	K_{f}	N/A_{rms}	36.3	19.9	36.3	19.9	36.3	19.9	36.3	19.9
	Motor constant	coils @ 25°C	S	N^2/W	24	24	47	47	71	73	95	94
	Peak current	magnets @ 25°C	I_p	A_{rms}	2.8	5.0	5.5	10	8.3	15	11	20
	Continuous current ¹	coils @ 110°C	Ic	A_{rms}	0.8	1.5	1.6	2.9	2.4	4.4	3.2	5.8
<u>a</u>	Continuous current ^{1,3}	coils @ 105°C	I_c	A_{rms}	0.8	1.4	1.6	2.8	2.3	4.2	3.1	5.7
Electrical	Back EMF ph-ph peak		K _e	V _{dc} /m/s	30	16	30	16	30	16	30	16
ä	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	18.5	5.5	9.3	2.8	6.2	1.8	4.6	1.4
	Induction per phase		L_ph	mH	6.5	1.8	3.3	0.9	2.2	0.6	1.5	0.4
	Electrical time constant		$\tau_{\rm e}$	ms				0.	35			
	Continuous power loss ¹	coils @ 110°C	P _c	W	4	17	95	5	14	12	19	00
a	Continuous power loss ^{1,3}	coils @ 105°C	$P_{\rm c}$	W	4	14	89)	13	33	17	'8
Thermal	Thermal resistance	coils to mount. sfc.	R _{th}	K/W	1	.8	0.9	9	0.	.6	0.4	1 5
Ė	Thermal time constant	up to 63% max. coil temp.	τ_{th}	S				3	36			
	Temperature sensor							PTC 1k	Ω / NTC			
	Coil unit mass	ex. cables	m	kg	0.1	100	0.16	52	0.2	40	0.3	18
	Coil unit length	ex. cables	L	mm	7	78	138	8	19	98	25	8
<u>ca</u>	Motor attraction force	rms @ 0 A	F_{a}	N					0			
Mechanical	Magnet pitch NN		τ	mm				3	80			
Mec	Cable mass			kg/m				0.	08			
	Cable type (power)	length 1 m	d	mm (AWG)				5.5	(22)			
	Cable type (sensor)	length 1 m	d	mm (AWG)				3.2	(26)			

¹ These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.

 $^{^{2}\,}$ Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.

³ The maximum coil temperature for CSA certification is 105°C. The maximum coil temperature without CSA certification is 110°C.

Magnet yokes Coil units





UL3 in 210mm magnet yoke shown

Magnet yoke dimensions								
Le (mm)	126	168	210	546				
M5 bolts	M5 bolts 3 4 5 13							
Mass (kg/m) 11.2								
Maanet vokes	ran he k	outted to	aether.					

TECNOTION° direct drive in motion

UL series ironless

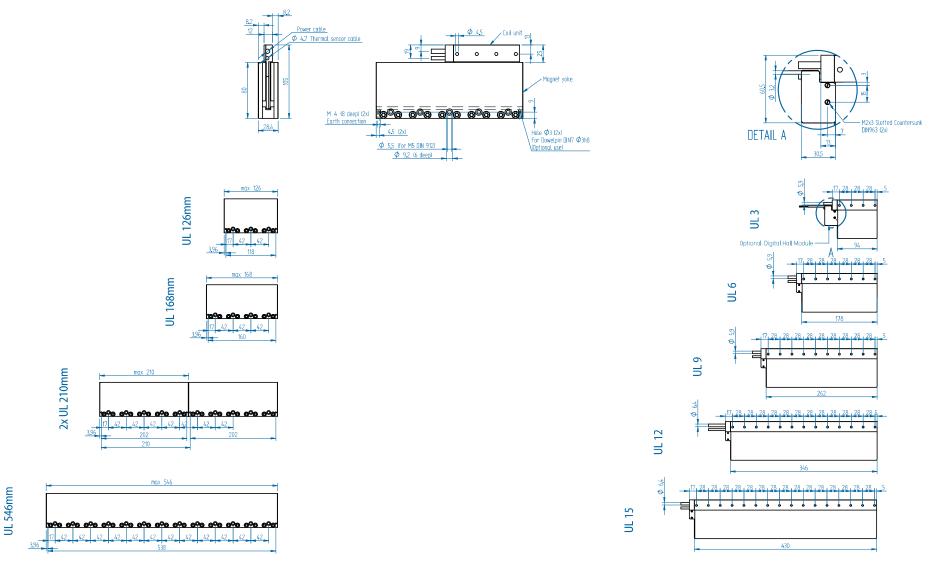
	Parameter	Remarks	Symbol	Unit	U	L3	U	L6	U	L9	UL	.12	UL	.15
	Winding type		•		N	S	N	S	N	S	N	S	N	S
	Motor type, max voltage ph-ph	3-phase synchronous	U _{max}	$V_{ac,rms}\left(V_{dc}\right)$					230	(325)				
e	Peak force @ 20 K/s increase	magnets @ 25°C	F_p	N	24	40	4	80	7:	20	90	50	12	00
man	Continuous force ¹	coils @ 110°C	F _c	N	7	0	14	40	2	10	28	80	35	50
Performance	Continuous force ^{1,3}	coils @ 105°C	Fc	N	6	7	1.	37	20	01	20	59	33	36
A.	Maximum speed ²	@ U _{max} @ F _c	V _{max}	m/s	5.0	12	5.0	12	5.0	12	5.0	12	5.0	12
	Motor force constant	$I \leq I_c$	K_{f}	N/A_{rms}	68	27.5	68	27.5	68	27.5	68	27.5	68	27.5
	Motor constant	coils @ 25°C	S	N ² /W	97	97	193	197	291	297	385	394	460	476
	Peak current	magnets @ 25°C	I_p	A_{rms}	3.5	8.7	7.1	17.5	10.6	26.2	14.1	35	17.8	44
	Continuous current ¹	coils @ 110°C	I _c	A_{rms}	1.0	2.6	2.1	5.1	3.1	7.6	4.2	10.2	5.2	12.9
<u>a</u>	Continuous current ^{1,3}	coils @ 105°C	l _c	A_{rms}	1.0	2.5	2.0	4.9	3.0	7.4	4.0	9.9	4.9	12.3
Electrical	Back EMF ph-ph peak		K _e	V _{dc} /m/s	55.5	22.5	55.5	22.5	55.5	22.5	55.5	22.5	55.5	22.5
ä	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	15.9	2.6	8.0	1.28	5.3	0.85	4.0	0.64	3.3	0.53
	Induction per phase		L_ph	mH	13	2.1	6.5	1.02	4.2	0.68	3.2	0.51	2.7	0.42
	Electrical time constant		τ_{e}	ms					0	.8				
	Continuous power loss ¹	coils @ 110°C	P _c	W	6	7	1:	34	20	00	2	70	33	35
<u>a</u>	Continuous power loss ^{1,3}	coi l s @ 105°C	P _c	W	6	2	1.	23	18	85	24	46	30)8
Thermal	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	1	.3	0.	65	0.	43	0.	32	0	26
F	Thermal time constant	up to 63% max. coil temp.	τ_{th}	S					7	'2				
	Temperature sensor								PTC 1k	Ω/NTC				
	Coil unit mass	ex. cables	m	kg	0.	27	0.	49	0.	69	0.	91	1.	13
	Coil unit length	ex. cables	L	mm	10	06	19	90	2	74	3.	58	44	12
ica	Motor attraction force	rms @ 0 A	Fa	N					(0				
Mechanical	Magnet pitch NN		τ	mm					4	12				
Me	Cable mass			kg/m			0.	09				0.1	05	
	Cable type (power)	length 1 m	d	mm (AWG)			5.9	(20)				6.4	(18)	
	Cable type (sensor)	length 1 m	d	mm (AWG)					4.7	(26)				

¹ These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.

 $^{^{2}\,}$ Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.

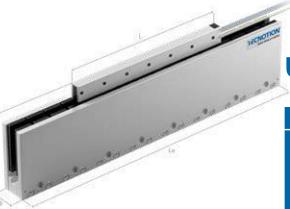
 $^{^3}$ The maximum coil temperature for CSA certification is 105°C. The maximum coil temperature without CSA certification is 110°C.

Magnet yokes Coil units



Mounting instructions and flatness or parallelism requirements can be found in the ironless installation manual. CAD files and 3D models can be downloaded from our website.

* All sizes are in mm



UXA6 in 456mm magnet yoke shown

UXA3S power cable (FLEX cable of 3m)						
Cable type	8.5 mm (21 AWG)					
Cable life ⁵	5,000,000 cycles					
Bending radius static	4x cable diameter					
Bending radius dynamic	10x cable diameter					
£						

⁵ Depending on bending radius, velocity and acceleration.

Magnet yoke dimensions									
Le (mm)	114	171	456						
M6 bolts	s 2 3 8								
Mass (kg/m) 19									
Magnet yokes can be butted together.									





UXA series ironless

	Parameter	Remarks	Symbol	Unit	UX	A3	UXA6		UXA9		UXA12		UXA18
	Winding type				N	S	N	S	N	S	N	S	N
	Motor type, max voltage ph-ph	3-phase synchronous	U_{max}	$V_{ac,rms} (V_{dc})$					230 (325)			
ə	Peak force @ 20 K/s increase	magnets @ 25°C	F_p	N	61	615		30	1845		2460		3690
Performance	Continuous force ¹	coils @ 110°C	F _c	N	12	20	2	40	36	50	48	30	720
rfor	Continuous force ^{1,3}	coi l s @ 105°C	F_c	N	11	9	2	39	35	58	47	77	716
a.	Maximum speed ²	@ U _{max} @ F _c	V _{max}	m/s	2.9	7.2	2.9	7.2	2.9	7.2	2.9	7.2	2.9
	Motor force constant	$ \mathbf{l} \leq \mathbf{l} _{c}$	K_{f}	N/A_{rms}	107	43.4	107	43.4	107	43.4	107	43.4	107
	Motor constant	coils @ 25°C	S	N ² /W	242	241	483	487	720	730	954	966	1468
	Peak current	magnets @ 25°C	I_p	A_{rms}	5.6	13.9	11.3	28	16.9	42	22.6	56	34
	Continuous current ¹	coi l s @ 110°C	I _c	A_{rms}	1.1	2.8	2.3	5.6	3.4	8.4	4.5	11.2	6.8
<u>e</u>	Continuous current ^{1,3}	coi l s @ 105°C	I _c	A_{rms}	1.1	2.7	2.2	5.5	3.3	8.2	4.5	10.9	6.7
Electrical	Back EMF ph-ph peak		K _e	V _{dc} /m/s	87	35	87	35	87	35	87	35	87
ä	Resistance per phase	coi l s @ 25°C ex. cable	R_{ph}	Ω	15.8	2.6	7.9	1.29	5.3	0.86	4.0	0.65	2.6
	Induction per phase		L_ph	mH	28	4.6	14	2.3	9.5	1.5	7.1	1.2	4.7
	Electrical time constant		τ_{e}	ms					1.8				
	Continuous power loss ¹	coils @ 110°C	P _c	W	8.	2	10	65	24	17	33	30	494
<u></u>	Continuous power loss ^{1,3}	coi l s @ 105°C	P_{c}	W	7	7	1.	54	23	31	30	8(462
Thermal	Thermal resistance	coils to mount. sfc.	R_{th}	K/W	1.0)4	0.	52	0.	35	0.3	26	0.17
Ė	Thermal time constant	up to 63% max. coil temp.	τ_{th}	S					156				
	Temperature sensor							P.	TC 1kΩ/1	NTC			
	Coil unit mass	ex. cables	m	kg	0.5	55	1.	06	1,	55	2.0	06	3.02
	Coil unit length	ex. cables	L	mm	13	4	2	48	36	52	47	76	704
ical	Motor attraction force	rms @ 0 A	F_a	N					0				
Mechanical	Magnet pitch NN		τ	mm					57				
Med	Cable mass			kg/m					0.105				
	Cable type (power) ⁴	length 1 m	d	mm (AWG)					6.5 (18)				
	Cable type (sensor)	length 1 m	d	mm (AWG)					4.7 (26)				

 $These values are only applicable when the mounting surface is at 20^{\circ}C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.$

² Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.

 $^{^3}$ The maximum coil temperature for CSA certification is 105° C. The maximum coil temperature without CSA certification is 110° C.

⁴ The UXA3S is only available with a FLEX power cable.

Coil units Magnet yokes Power cable

4.7 Thermal sensor cable - Magnet yoke - M2x3 Slotted Countersunk DIN963 (2x) DETAIL A 38.1 Hole **Ø**3 (2x) For Dowelpin DIN7 **Ø**3h8 (<mark>Optional use)</mark> ϕ 6.5 (for M6 DIN 912) Ø 11 (8 deep) UXA 114mm 1000 0001 Optional: Digital Hall Module 122 9 XN UXA 171mm 6 XN 2x UXA 114mm UX 12 UXA 456mm UX 18 φ 6.5

Mounting instructions and flatness or parallelism requirements can be found in the ironless installation manual. CAD files and 3D models can be downloaded from our website.

* All sizes are in mm

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UXX3S power cable	(FLEX cable of 3m)
Cable type	8.5 mm (21 AWG)
Cable life ⁵	5,000,000 cycles
Bending radius static	4x cable diameter
Bending radius static	10x cable diameter

⁵ Depending on bending radius, velocity and acceleration.

Magnet yoke dimensions						
Le (mm)	114	171	456			
M6 bolts	2	3	8			
Mass (kg/m) 25						
Magnet yokes can be butted together.						



	Parameter	Remarks	Symbol	Unit	UX	(X3	UX	X6	UX	Х9	UXX	(12	UXX18
	Winding type				N	S	N	S	N	S	N	S	N
	Motor type, max voltage ph-ph	3-phase synchronous	U _{max}	V _{ac,rms} (V _{dc})	230 (325)								
e	Peak force @ 20 K/s increase	magnets @ 25°C	F_p	N	700 1400		00	2100		2800		4200	
man	Continuous force ¹	coils @ 110°C	F _c	N	141		282		423		564		846
Performance	Continuous force ^{1,3}	coils @ 105°C	F_c	N	138 277		77	415		553		830	
P	Maximum speed ²	@ U _{max} @ F _c	V _{max}	m/s	2.7	6.6	2.7	6.6	2.7	6.6	2.7	6.6	2.7
	Motor force constant	$ I \leq I _c$	K_f	N/A_{rms}	124	50.3	124	50.3	124	50.3	124	50.3	124
	Motor constant	coils @ 25°C	S	N^2/W	324	324	649	654	967	981	1281	1297	1971
	Peak current	magnets @ 25°C	I_p	A_{rms}	5.6	13.9	11.3	28	16.9	42	22.6	56	34
	Continuous current ¹	coils @ 110°C	I _c	A _{rms}	1.1	2.8	2.3	5.6	3.4	8.4	4.5	11.2	6.8
e	Continuous current ^{1,3}	coils @ 105°C	I _c	A_{rms}	1.1	2.7	2.2	5.5	3.3	8.2	4.5	10.9	6.7
Electrical	Back EMF ph-ph peak		K _e	V _{dc} /m/s	101	41	101	41	101	41	101	41	101
	Resistance per phase	coils @ 25°C ex. cable	R_{ph}	Ω	15.8	2.6	7.9	1.29	5.3	0.86	4.0	0.65	2.6
	Induction per phase		L _{ph}	mH	28	4.6	14	2.3	9.5	1.5	7.1	1.2	4.7
	Electrical time constant		$\tau_{\rm e}$	ms					1.8				
	Continuous power loss ¹	coils @ 110°C	P _c	W	8	32	16	55	24	17	33	0	494
<u>a</u>	Continuous power loss 1,3	coils @ 105°C	Pc	W	7	7	15	54	23	31	30	18	462
Thermal	Thermal resistance	coils to mount. sfc.	R _{th}	K/W	1.	04	0.	52	0	35	0.2	26	0.17
f	Thermal time constant	up to 63% max. coil temp.	$ au_{\text{th}}$	S					156				
	Temperature sensor							P ⁻	ΓC 1kΩ / N	TC			
	Coil unit mass	ex. cables	m	kg	0.55		1.06		1.55		2.06		3.02
	Coil unit length	ex. cables	L	mm	134		248		362		476		704
ica	Motor attraction force	rms @ 0 A	Fa	N				0	0				
Mechanical	Magnet pitch NN		τ	mm			57						
Med	Cable mass			kg/m					0.105				
	Cable type (power) ⁴	length 1 m	d	mm (AWG)					6.5 (18)				
	Cable type (sensor)	length 1 m	d	mm (AWG)					4.7 (26)				

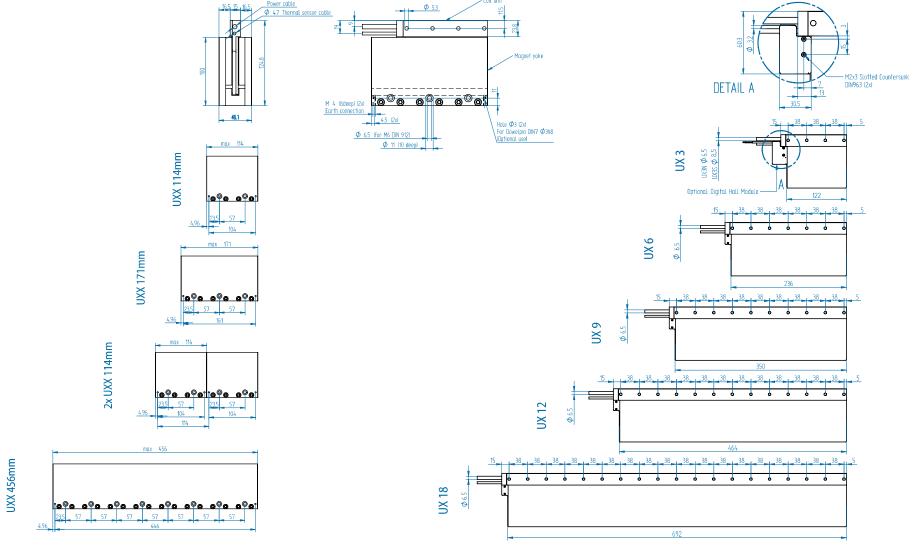
¹ These values are only applicable when the mounting surface is at 20°C and the motor is driven at continuous current. If these values differ in your application, please check our simulation tool.

 $^{^{2}}$ Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.

 $^{^3}$ The maximum coil temperature for CSA certification is 105°C. The maximum coil temperature without CSA certification is 110°C.

⁴ The UXX3S is only available with a FLEX power cable.

Magnet yokes Coil units



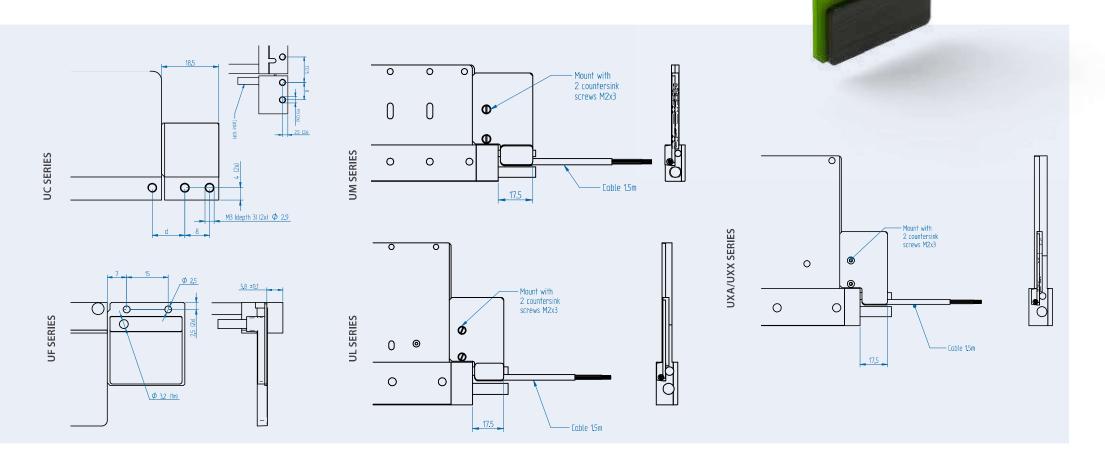
Mounting instructions and flatness or parallelism requirements can be found in the ironless installation manual. CAD files and 3D models can be downloaded from our website.

* All sizes are in mm

Digital Hall module for commutation

Digital Hall sensors can be used to determine the position of the coil unit within the magnetic field for a controller to correctly commutate the phases. If you do not use a controller that allows you to commutate within the servo drive, this module can be a cost-effective alternative.

Each ironless motor series has its own additional digital Hall module. Resolutions of the digital Hall modules are: UC: 2.75 mm; UF: 4 mm; UM: 5 mm; UL: 7 mm; UXA/UXX: 9.5 mm.







Support

At Tecnotion, we recognize that every use of our motors presents unique circumstances with different needs and challenges. Our team of Sales and Application Engineers have extensive experience in different application scenarios and work closely with our customers to find solutions that perfectly align with their requirements and objectives.

With our commitment to excellence and innovation, we remain steadfast in our mission to provide our customers with solutions that lead them to success in an ever-changing landscape.

Continuous innovation

At the heart of our company is an internal Research and Development (R&D) department that serves as an engine for innovation. This dedication to innovation not only fuels our deep knowledge of manufacturing processes, but also drives our commitment to excel in product design and performance, helping our customers meet the changing needs and expectations of their customers.

In addition to our extensive range of off-the-shelf standard motors, we custom design motors for applications that have more unique requirements. Our team works closely with customers to understand their specific challenges and objectives.

Modern manufacturing

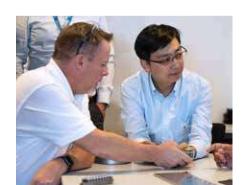
Our manufacturing capabilities are strategically distributed between our facilities in China, Vietnam and the Netherlands, each of which plays a vital role in delivering first-class products to our customers worldwide. This distribution enables us to meet the demands of mass production.

Our competence centre and headquarters in the Netherlands are dedicated to advanced motor technology and are the epicentre of innovation and precision engineering. Custom motors are also built here in our special state-of-the-art clean room environment, with extreme precision and an eye for quality. Tecnotion prides itself on maintaining the strictest quality standards in all facets of our operations. Our plants are ISO 9001 certified.

Global logistics

We ensure that our most popular products are in stock in our warehouses. This setup gives us quick access to our stock, regardless of your location. Whether you are near our European headquarters or on the other side of the world, our efficient shipping network ensures that your orders are processed quickly.

Even during periods of increased market activity, our flexible supply chain allows us to maintain fast delivery times, so your products reach you quickly and reliably. With our unwavering commitment to customer satisfaction and operational excellence, we strive to provide seamless and efficient service throughout the supply chain.





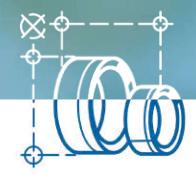


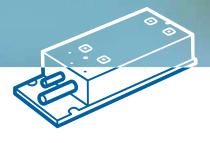


We direct drive your motion technology









Vacuum linear motors

F_p 100-4020 N F_c 22-698 N

Vacuum Generation 2 motors for powerful and precise processes

Generation 2 vacuum ironless linear motor series is designed with the unique challenges of vacuum applications in mind and based on years of collaboration with high-end semiconductor manufacturers.

Optimal thermal properties, added safety, excellent RGA performance, lower outgassing and flexibility to install, make the Generation 2 vacuum motor series the benchmark for motion in vacuum applications.

www.tecnotion.com/vacuum

Torque motors

T_u 0.64-2202 Nm T_c 0.29-907 Nm

Increased accuracy and dynamic performance of your application

Tecnotion torque motor series features superior force density, low thermal resistance, low cogging and housed design. Motors can be very slim in height but large in diameter (for large axles and turntables) or have a 'height' close to their diameter, resulting in a compact but high-torque motor.

The torque series consists of different outer diameters ranging from 65mm to 485mm for the largest motor and various building heights ranging from 17mm up to 105mm. www.tecnotion.com/torque

Custom motors

Motor solutions

Adapt standard motor series to meet your needs

In case the standard motor series are not sufficient for your application, it is also possible to have these motors customized in a variety of ways. Customization can range from simple modifications, like adding a connector, to fully tailor-made motors designed from scratch.

Some examples: custom windings, cable confection, additional sensors, additional certifications and customization for vacuum applications. For more information please contact Tecnotion.

www.tecnotion.com/custom

Iron core linear motors

F_u 120-6750 N F_c 60-3000 N

Extremely high force in a modular compact design

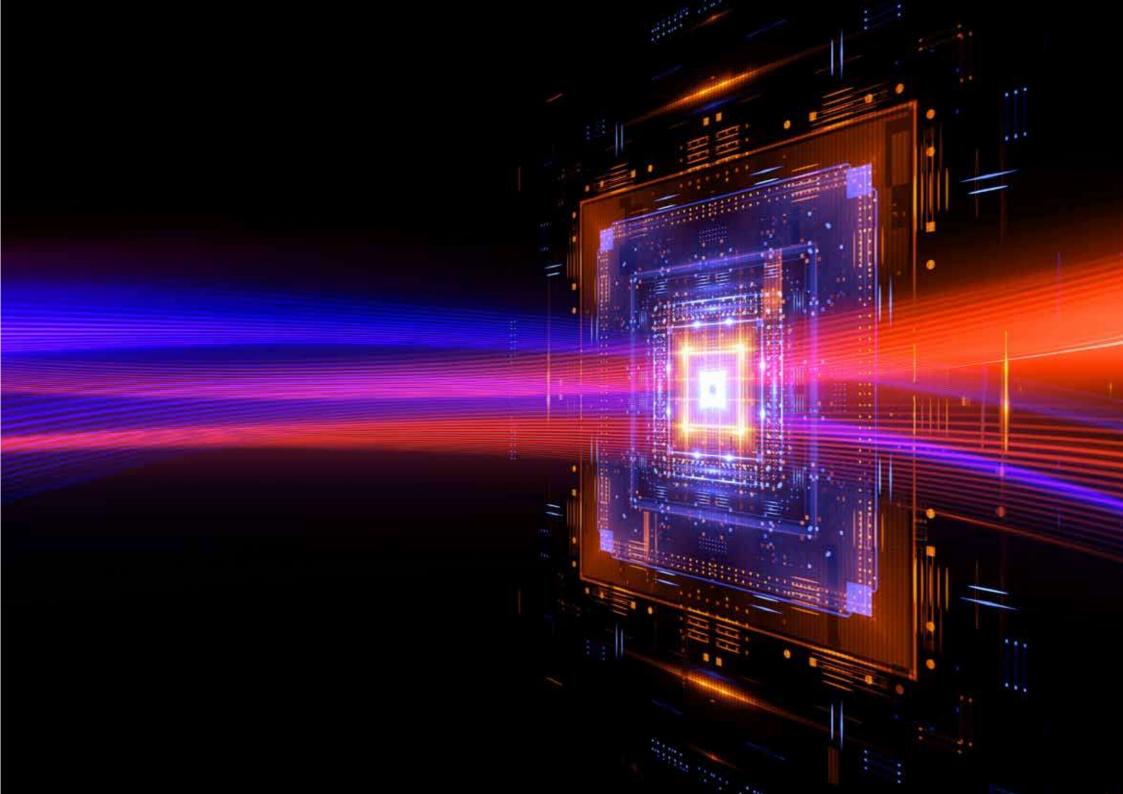
Designed and constructed with an iron core, these series offer an extremely high continuous force for their size, starting at 60 N for the small TM, up to 3000 N for the water cooled TBW. Peak forces are even higher, reaching up to 6000 N.

A small footprint, modular design, and high force density enable very flexible application designs, using iron core linear motors. Suitable for many applications such as printing, digital cutting, and machine tooling.

www.tecnotion.com/ironcore









Article numbers

Series	Article	Article code				
UC series						
UC	Coil unit UC 3	4022 368 5067				
UC	Coil unit UC 3 inline	4022 368 5516				
UC	Coil unit UC 6	4022 368 5068				
UC	Magnet yoke UC 66 mm	4022 368 5064				
UC	Magnet yoke UC 99 mm	4022 368 5065				
UC	Magnet yoke UC 264 mm	4022 368 5066				
UC	Digital Hall Module UC	4022 368 5130				
UF series						
UF	Coil unit UF 3	4022 368 5298				
UF	Coil unit UF 6	4022 368 5372				
UF	Magnet yoke UF 72 mm	4022 368 5382				
UF	Magnet yoke UF 120 mm	4022 368 5383				
UF Digital Hall Module UF		4022 368 5391				
UM series						
UM Coil unit UM 3N		4022 368 5055				
UM	Coil unit UM 3S	4022 368 5051				
UM	Coil unit UM 6N	4022 368 5056				
UM	Coil unit UM 6S	4022 368 5052				
UM	Coil unit UM 9N	4022 368 5057				
UM	Coil unit UM 9S	4022 368 5053				
UM	Coil unit UM 12N	4022 368 5058				
UM	Coil unit UM 12S	4022 368 5054				
UM	Magnet yoke UM 90 mm	4022 368 5040				
UM	Magnet yoke UM 120 mm	4022 368 5041				
UM	Magnet yoke UM 150 mm	4022 368 5042				
UM	Magnet yoke UM 390 mm	4022 368 5043				
UM	Digital Hall Module UM	4022 368 5144				
UL series						
UL	Coil unit UL 3N	4022 368 5025				
UL	Coil unit UL 3S	4022 368 5045				

Series	Article	Article code				
UL	Coil unit UL 6N	4022 368 5026				
UL	Coil unit UL 6S	4022 368 5046				
UL	Coil unit UL 9N	4022 368 5027				
UL	Coil unit UL 9S	4022 368 5047				
UL	Coil unit UL 12N	4022 368 5028				
UL	Coil unit UL 12S	4022 368 5048				
UL	Coil unit UL 15N	4022 368 5029				
UL	Coil unit UL 15S	4022 368 5049				
UL	Magnet yoke UL 126 mm	4022 368 5021				
UL	Magnet yoke UL 168 mm	4022 368 5022				
UL	Magnet yoke UL 210 mm	4022 368 5023				
UL	Magnet yoke UL 546 mm	4022 368 5024				
UL Digital Hall Module UL		4022 368 5145				
UXA/UXX series						
UXA/UXX	Coil unit UX 3N	4022 368 5105				
UXA/UXX	Coil unit UX 3S FLEX	4022 368 5235				
UXA/UXX	Coil unit UX 6N	4022 368 5106				
UXA/UXX	Coil unit UX 6S	4022 368 5101				
UXA/UXX	Coil unit UX 9N	4022 368 5107				
UXA/UXX	Coil unit UX 9S	4022 368 5102				
UXA/UXX	Coil unit UX 12N	4022 368 5108				
UXA/UXX	Coil unit UX 12S	4022 368 5103				
UXA/UXX	Coil unit UX 18N	4022 368 5111				
UXA	Magnet yoke UX-A 114 mm	4022 368 5098				
UXA	Magnet yoke UX-A 171 mm	4022 368 5093				
UXA	Magnet yoke UX-A 456 mm	4022 368 5099				
UXX	Magnet yoke UXX 114 mm	4022 368 5215				
UXX	Magnet yoke UXX 171 mm	4022 368 5216				
UXX	Magnet yoke UXX 456 mm	4022 368 5217				
UXA/UXX	Digital Hall Module UX	4022 368 5154				



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